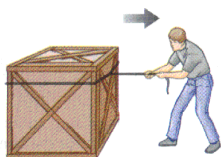


I. Force (2.1)

A. **force**— is a push or pull

1. A **force** is needed to change an object's state of motion
2. State of motion may be one of two things

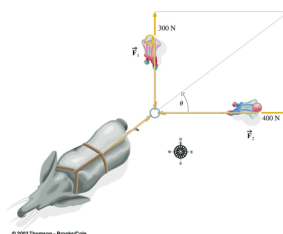
a. At rest



b. Moving uniformly along a straight-line path.

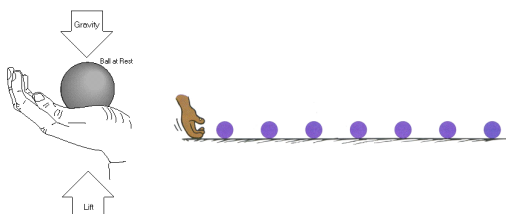
B. Net force

1. Usually more than one force is acting on an object
2. **combination of all forces** acting on object is called **net force**.



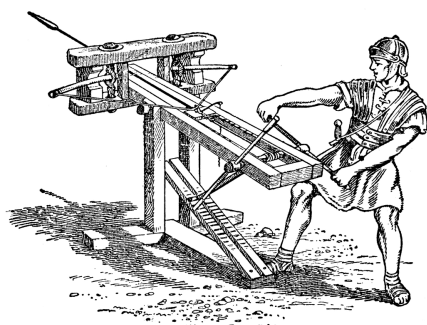
3. The net force on an object changes its **motion**

4. Can **add** or **subtract** to get resultant net force
5. If forces acting on object equal **zero** then we say the **net force** acting on the **object = 0**
6. Scientific units for force are **Newtons (N)**



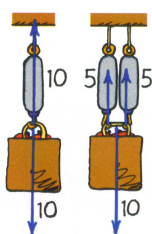
C. Tension and Weight

1. **Tension** is a "**stretching force**"



2. When you hang an object from a spring scale the there are two forces acting on object.

- a. **Force of gravity** pulling down (also called **weight**)



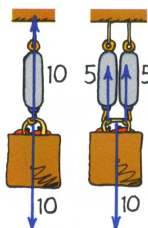
- b. **Tension** force pulling upward

- c. Two forces are **equal** and **opposite in direction** and add to zero (**net force = 0**)

D. Force Vectors

1. Forces can be represented by **arrows**

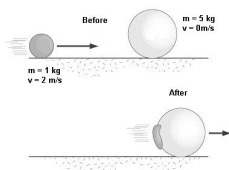
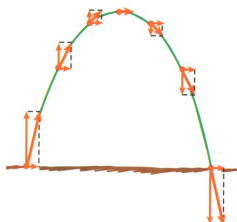
a. **length** of arrow represents **amount (magnitude)** of force



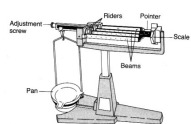
b. **Direction** of arrow represents **direction of force**

c. Refer to arrow as a **vector** (represents both **magnitude** and **direction** of force)

2. **Vector quantity**- needs both **magnitude** and **direction** to complete description (i.e. force, velocity, momentum)



3. **Scalar quantity**- can be described by **magnitude only** and has no direction (i.e. temperature, speed, distance)

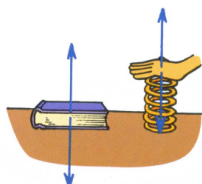


II. Mechanical Equilibrium (2.2)

A. Mechanical equilibrium- a state wherein **no physical changes occur** (state of steadiness)

1. When **net force equals zero**, object is said to be in **mechanical equilibrium**

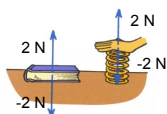
a. Known as **equilibrium rule**



b. Can express rule **mathematically** as

$$\Sigma F = 0$$

- 1). Σ symbol stands for “the sum of”
- 2). **F** stands for “forces”

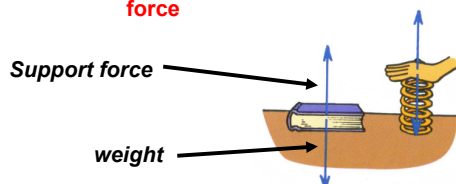


$$\Sigma F = (2 - 2) = 0$$

III. Support Force (2.3)

A. **support force**- the **upward** force that balances the weight of an object on a **surface**

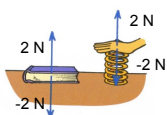
1. The upward force balances the **weight** of an object
2. Support force often called **normal force**



B. For an object at **rest** on a horizontal surface, the **support force** must equal the objects **weight**.

1. Upward force is positive (+) and the downward force is negative (-).
2. Two forces add mathematically to zero

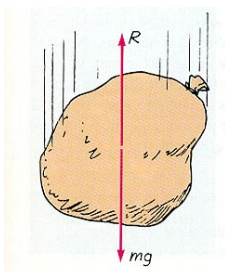
$$\Sigma F = 0$$



$$\Sigma F = (2 - 2) = 0$$

IV. Equilibrium of Moving Objects (2.4)

A. Equilibrium can exist in both objects at rest and objects moving at constant speed in a straight-line path.



1. **Equilibrium** means **state of no change**
2. **Sum of forces equal zero**

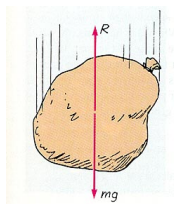
$$\Sigma F = 0$$

B. Objects at rest are said to be in **static equilibrium**

C. Objects moving at constant speed in a straight-line path are said to be in **dynamic equilibrium**



Static equilibrium

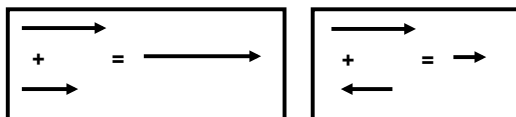


dynamic equilibrium

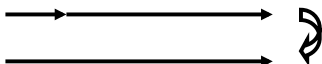
V. Vectors (2.5)


A. **Parallel vectors**

1. **Add** vectors if in **same direction**
2. **Subtract** vectors if in **opposite direction**
3. The sum of two or more vectors is called the **resultant vector**.



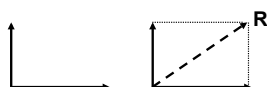
B. **Parallel vectors**— simple to add or subtract

add 

subtract 

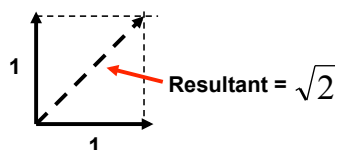
C. **Non-parallel vectors**

1. Construct a **parallelogram** to determine **resultant vector**
2. The **diagonal** of the parallelogram shows the **resultant**

a. **Perpendicular vectors**

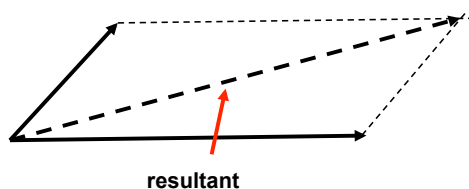
b. Perpendicular vectors with **equal** sides (special case)

- 1). For a square the length of diagonal is $\sqrt{2}$ or 1.414
- 2). **Resultant = 1.414 x one of sides**

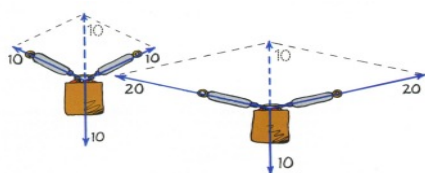


c. Parallelogram (**not perpendicular**)

- Construct parallelogram
- Construct with two vectors as sides
- Resultant is the diagonal

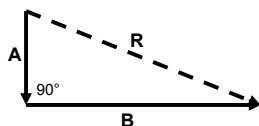


C. Applying the Parallelogram Rule- as angle increases, tension increases.



Pythagorean Theorem- can be used if vectors added are at **right angles**

$$R^2 = A^2 + B^2 \text{ or } R = \sqrt{A^2 + B^2}$$



SOHCAHTOA

- **sin**, **cos**, and **tan** are functions of the angle of a triangle compared to the lengths of the sides of a triangle
- If you know the distances of the triangle sides, you can determine the inside angles.
- If you know the angle and one side, you can calculate the length of the other side of the triangle.
- Remember the following acronym: **SOHCAHTOA**
- These will give you the formula depending on which side or angle you need to calculate

$$\sin \theta = \left(\frac{O}{H} \right)$$

$$\cos \theta = \left(\frac{A}{H} \right)$$

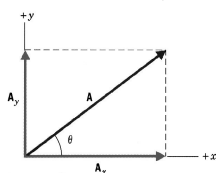
$$\tan \theta = \left(\frac{O}{A} \right)$$

Components calculated using following **formulas**

$$A_x = A \cos \theta; \text{therefore, } \cos \theta = \left(\frac{\text{adjacent}}{\text{hypotenuse}} \right) = \left(\frac{A_x}{A} \right)$$

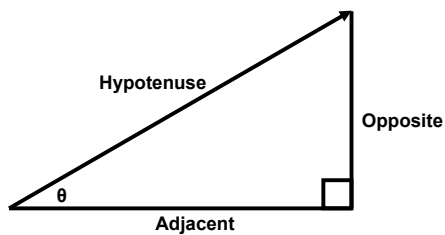
$$A_y = A \sin \theta; \text{therefore, } \sin \theta = \left(\frac{\text{opposite}}{\text{hypotenuse}} \right) = \left(\frac{A_y}{A} \right)$$

When angles larger than 90° , sign of one or more components may be **negative**



Second Quadrant	First Quadrant
$A_x < 0$	$A_x > 0$
$A_y > 0$	$A_y > 0$
Third Quadrant	Fourth Quadrant
$A_x < 0$	$A_x > 0$
$A_y < 0$	$A_y < 0$

- Remember what the sides of a triangle are called

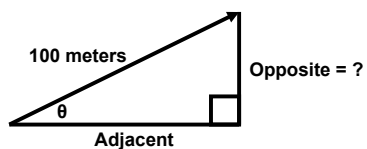


Example:

$$\sin 25^\circ = \frac{\text{Length of Opposite side}}{\text{Length of Hypotenuse}}$$

$$\sin 25^\circ = \frac{\text{Length of Opposite side}}{100 \text{ meters}}$$

$$\text{length of Opposite side} = 38.3 \text{ meters}$$



Graphical Addition of Vectors

• Simple method for combining vectors to get resultant vector

• Use **ruler** to measure **length** of vector

• Use **protractor** to measure **angle**

